Original Article

# Bohl Theorem for Volterra Equations 

Nguyen Thu Ha*<br>Electric Power University, 235 Hoang Quoc Viet, Cau Giay Hanoi, Vietnam

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#### Abstract

This work deals with the preservation of exponential stability under small perturbations for Volterra differential equations. The so-called Bohl-Perron type stability theorems for these systems are also studied.


Keywords: Hardy inequality, time scales, exponential function.

## 1. Introduction

The Volterra differential equations play an important role in studying mathematical models because for almost systems in ecology, economy, the evolution of present time depends on the past history of the systems. Therefore, studying the robust stability of systems is important both in theory and practice since the system always operates under the effect of uncertain perturbations. One can deal with the robust stability by many ways. Some research groups measured the robust stability by using the socalled stability radii for linear systems [1, 2] or carried-out some estimates of the perturbation ensuring the stability of perturbed systems [3, 4]. Also, the other method to study robust stability is to consider Bohl-Perron theorem, which establishes a relation between the Liapunov stability of homogeneous differential equations in initial conditions and the boundedness of solutions of inhomogeneous one. We can refer to [5-7] to get some results on this problem for ordinary or delay linear differential equation.

The aim of this work is to study the robust stability and Bohl-Perron theorem for the Volterra integrodifferential equation

$$
\begin{equation*}
x^{\prime}(t)=A(t) x(t)+\int_{0}^{t} H(t, s) x(s) d \mu(s)+f(t), \quad t \geq 0 \tag{1}
\end{equation*}
$$

where $\mu$ is a radon measure on $\left(\square^{+}, B\left(\square^{+}\right)\right)$and $A(),. H(.,$.$) are specified later.$

[^0]Firstly, we deal with the preservation of stability for the linear Volterra integro-differential Eq. (1) under small perturbations and then we study Bohl-Perron theorem. Since the derivative of state process $\mathrm{x}(\mathrm{t})$ depends on all past path $x(s), 0 \leq s \leq t$, we have to use a more general inequality of GronwallBellman type to obtain the upper bound of perturbations. Further, the Cauchy operator of the corresponding homogeneous equation does not have the semi-group property, which implies that the classical argument to solve this problem is no longer valid. To overcome it, we define weighed spaces $L^{\gamma}([0, \infty), X)$ and $C^{\gamma}([0, \infty), X)$ (see Definitions below) and consider operators acting between these spaces. The paper is organized as follows. In the next section we recall some basic properties of linear Volterra integro-differential with measures and prove the existence of solutions. In Section 3, we prove that if the linear Volterra equations are exponentially stable, then under small Lipschitz perturbations, the perturbed system is $L_{p}$ stable. Section 4 presents the famous Bohl-Perron Theorem for Eq. (1). We introduce some weighted spaces and consider the solutions of Eq. (1) as elements of these spaces. Hence, we show that the exponential stability is equivalent to the surjectivity of certain operators. Some examples are introduced to illustrate the results.

## 2. Linear Volterra Differential Equations

Let $X$ be a Banach space and $L(X)$ be the space of the continuous linear transformations on $X$. Let $A():.[0, \infty) \rightarrow L(X)$ is a continuous function valued in $L(X)$ and $H(.,$.$) is a two variable continuous$ function defined on the set $\{(t, s): 0 \leq s \leq t<\infty\}$, valued in $L(X)$. For any continuous function $q:[0, \infty) \rightarrow X$ we consider the linear integro-differential Volterra system

$$
\left\{\begin{array}{l}
x^{\prime}(t)=A(t) x(t)+\int_{0}^{t} H(t, s) x(s) d \mu(s)+q(t), \quad t \geq 0  \tag{2}\\
x(0)=x_{0}
\end{array}\right.
$$

where $\mu$ is a random measure on $\left(\square^{+}, B\left(\square^{+}\right)\right)$. This means that $\mu$ is a measure and $\mu(M)<+\infty$ for every compact $M \subset \square^{+}$. We note that although $H(.,$.$) is a two variables continuous function, the$ mapping $t \rightarrow \int_{0}^{t} H(t, s) x(s) d \mu(s)$ may be discontinuous at some points (at most in a countable set). Therefore, we have to understand the solution $x$ of the initial problem in Eq. (2) in Carathéodory sense, i.e., $x($.$) is continuous and it is differentiable almost every where with respect to Lebesgue measure on$ $\square^{+}$. In other words, the function $x($.$) is a solution of Eq. (2) with the initial condition x(0)=x_{0}$ if and only if it satisfies the equation:

$$
\begin{equation*}
x(t)=x(0)+\int_{0}^{t} A(t) x(t) d t+\int_{0}^{t} \int_{0}^{\tau} H(\tau, s) x(s) d \mu(s) d \tau+\int_{0}^{t} q(\tau) d \tau, \quad t \geq 0 \tag{3}
\end{equation*}
$$

Proposition 2.1 The initial value problem in Eq. (2) has a unique solution.
Proof. Let $T>0$ fixed. Construct a sequence of Picard approximations

$$
\begin{align*}
x_{0}(t) & =x(0), \quad 0 \leq t \leq T \\
x_{n+1}(t) & =x(0)+\int_{0}^{t} A(\tau) x_{n}(\tau) d \tau+\int_{0}^{t} \int_{0}^{\tau} H(\tau, s) x_{n}(s) d \mu(s) d \tau+\int_{0}^{t} q(\tau) d \tau \tag{4}
\end{align*}
$$

It is seen that

$$
\left\|x_{n+1}(t)-x_{n}(t)\right\|=\int_{0}^{t}\left\|A(\tau)\left(x_{n}-x_{n-1}\right)(\tau)\right\| d \tau+\int_{0}^{t} \int_{0}^{\tau}\left\|H(\tau, s)\left(x_{n}-x_{n-1}\right)(s)\right\| d \mu(s) d \tau
$$

Therefore,

$$
\sup _{0 \leq \tau \leq T}\left|x_{n+1}(\tau)-x_{n}(\tau)\right|=K \int_{0}^{t} \sup _{0 \leq \tau \leq s}\left\|\left(x_{n}-x_{n-1}\right)(\tau)\right\| d s
$$

where $K=\sup _{0 \leq \tau \leq T}\|A(\tau)\|+\mu([0, T]) \sup _{0 \leq s \leq t \leq T} \leq\|H(t, s)\|$. By induction we get

$$
\begin{aligned}
& \sup _{0 \leq \tau \leq T}\left\|\left(x_{n+1}-x_{n}\right)(\tau)\right\| \leq K \int_{0}^{t} \sup _{0 \leq \tau \leq s}\left\|\left(x_{n}-x_{n-1}\right)(\tau)\right\| d s \\
& \quad \leq K^{2} \int_{0}^{t}\left(\int_{0}^{s} \sup _{0 \leq u \leq \tau}\left\|\left(x_{n-1}-x_{n-2}\right)(u)\right\| d u\right) d s \leq \frac{(T K)^{n-1}}{(n-1)!} .
\end{aligned}
$$

Hence, by using Weierstrass criterion for uniform convergence of series we see that

$$
x(t)-x_{0}=\sum_{k=1}^{\infty}\left(x_{k}(\tau)-x_{k-1}(\tau)\right)=\lim _{n \rightarrow \infty} x_{n}(t)-x_{0}
$$

is a continuous function. By passing the limit as $n \rightarrow \infty$ in Eq. (4) we have

$$
x(t)=x(0)+\int_{0}^{t} A(t) x(t) d t+\int_{0}^{t} \int_{0}^{t} H(t, s) x(s) d \mu(s) d t+\int_{0}^{t} q(t) d t, \quad t \geq 0,
$$

i.e., $x($.$) is the solution of (3) with the initial condition x(0)=x_{0}$. The proof is complete.

The homogeneous equation corresponding with Eq. (2), i.e., $q \equiv 0$ is

$$
\left\{\begin{array}{l}
x^{\prime}(t)=A(t) x(t)+\int_{0}^{t} H(t, s) x(s) d \mu(s), t \geq 0,  \tag{5}\\
x(0)=x_{0} .
\end{array}\right.
$$

We define the Cauchy operator $\Phi(t, s), t \geq s \geq 0$, generated by the system (2.4) as the solution of the matrix equation:

$$
\left\{\begin{array}{l}
\Phi^{\prime}(t, s)=A(t) \Phi(t, s)+\int_{0}^{t} H(t, s) \Phi(\tau, s) d \mu(\tau), t \geq s \geq 0  \tag{6}\\
\Phi(s, s)=I
\end{array}\right.
$$

As it is mentioned above, the mapping $t \rightarrow \Phi(t, s)$ is continuous and it is differentiable almost every, where $t \in[s, \infty)$. We have the following useful lemma, called the variation of constants formula,

Lemma 2.2 The solution of the Volterra equation (2.1) can be expressed as

$$
\begin{equation*}
x(t)=\Phi(t, 0) x_{0}+\int_{0}^{t} \Phi(\tau, \rho) q(\rho) d \rho \tag{7}
\end{equation*}
$$

Proof. We have

$$
\begin{aligned}
\int_{0}^{t}[A(\tau) & \left.\int_{0}^{\tau} \Phi(\tau, u) q(u) d u+\int_{0}^{\tau} H(\tau, s)\left(\int_{0}^{s} \Phi(s, u) q(u) d u\right) d \mu(s)+q(\tau)\right] d \tau \\
& =\int_{0}^{t}\left[A(\tau) \int_{0}^{\tau} \Phi(\tau, u) q(u) d u+\int_{0}^{\tau}\left(\int_{u}^{\tau} H(\tau, s) \Phi(s, u) d \mu(s)\right) q(u) d u+q(\tau)\right] d \tau \\
& =\int_{0}^{t}\left[\int_{0}^{\tau}\left(A(\tau) \Phi(\tau, u) q(u) d u+\int_{u}^{\tau} H(\tau, s) \Phi(s, u) d \mu(s)\right) q(u) d u+q(\tau)\right] d \tau \\
& =\int_{0}^{t}\left[\int_{0}^{\tau} \frac{d}{d \tau} \Phi(\tau, u) q(u) d u+q(\tau)\right] d \tau=\int_{0}^{t} q(u)\left(\int_{u}^{\tau} \frac{d}{d \tau} \Phi(\tau, u) d \tau\right) d u+\int_{0}^{t} q(\tau) d \tau \\
& =\int_{0}^{t} \Phi(t, u) q(u) d u=x(t) .
\end{aligned}
$$

Since the semi-group property of the Cauchy operator does not hold for the Volterra Eq. (5), we have to use another technique to study the Bohl-Perron Theorem for Volterra Equations.

Definition 2.3 i) The Volterra equation (5) is uniformly bounded if there exists a positive number $C_{0}$ such that

$$
\|\Phi(t, s)\| \leq C_{0}, t \geq s \geq 0 .
$$

ii) Let $\omega>0$. The Volterra equation (2.4) is $\omega$-exponentially stable if there exists a positive number $M$ such that

$$
\|\Phi(t, s)\| \leq M e^{-\omega(t-s)}, t \geq s \geq 0
$$

The conditions ensuring the boundedness or stability of the equation (5) can be referred to [6,8,9] and references therein.

## 3. Stability of Volterra integro-differential Equation Under Small Perturbations

In this section, we consider the effect of small perturbations to the stability of the Volterra Eq. (5). Let $f(t, s, x)$ and $g(t, x)$ be two continuous functions. Suppose that for every $s \leq t$ and $x \in X$, the coefficients $H(t, s) x$ and $A(t) x$ of Eq. (5) are perturbed by f and g . Thus, they become $H(t, s) x \mapsto$ $H(t, s) x+f(t, s, x)$ and $A(t) x \mapsto A(t) x+g(t, x)$. Thus, for any $t_{0} \geq 0$, the Cauchy problem for the perturbed Eq. (5) has following form:
$\left\{\begin{array}{l}x^{\prime}(t)=A(t) x(t)+\int_{0}^{t} H(t, s) x(s) d \mu(s)+\int_{0}^{t} f(t, s, x(s)) d \mu(s)+g(t, x(t)), t \geq 0 \\ x(0)=x_{0}\end{array}\right.$
Suppose further that $f(t, s, x)$ is Lipschitz in x with Lipschitz coefficients $k_{t, s}$ and $g(t, x)$ is Lipschitz with Lipschitz coefficient $l_{t}$, where $k_{t, s}, t \geq s \geq 0$, and $l_{t}, t \geq 0$ are continuous functions. One can suppose that

$$
f(t, s, 0)=0, \quad g(t, 0)=0, \quad t \geq s \geq 0
$$

With these assumptions, Eq. (8) has the trivial solution $x(.) \equiv 0$.
By a similar as in the proof of Proposition 2.1 we can show that for any $x_{0} \in X$ and $t_{0} \geq 0$, Eq. (8) has a unique solution, namely $x\left(., t_{0}, x_{0}\right) \equiv 0$, with the initial condition $x\left(t_{0}, t_{0}, x_{0}\right)=x_{0}$ and this solution is defined on $t \geq t_{0}$.

In the following, we write simply $x($.$) or x\left(., t_{0}\right)$ for $x\left(., t_{0}, x_{0}\right)$ if there is no confusion. To proceed, we need the following lemma.

Lemma 3.1 (Pachpatte inequality see [10]). Let the functions $u(t), \sigma(t), v(t), \omega(t, r)$ be nonnegative and continuous for $a \leq r \leq t$, and let $c_{1}$ and $c_{2}$ be nonnegative. If for $\left.t \in a, \infty\right)$,

$$
u(t) \leq c_{1}+c_{2} \int_{a}^{t}\left(v(s) u(s)+\int_{a}^{s} \omega(s, r) u(r) d \mu(r)\right) d s
$$

then for $t \geq a$,

$$
u(t) \leq c_{1} \exp \left\{c_{2} \int_{a}^{t}\left(v(s)+\int_{a}^{s} \omega(s, r) d \mu(r)\right) d s\right\} .
$$

Firstly, we consider the boundedness of solutions \{of Eq. (5) under small perturbations.
Theorem 3.2 Suppose that the solution of Eq. (5) is uniformly bounded. Then, there exists a constant $M_{1}$ such that the following estimate:

$$
\begin{equation*}
\|x(t)\| \leq M_{1}\left\|x\left(t_{0}\right)\right\|, \quad t \geq t_{0} \tag{9}
\end{equation*}
$$

holds for solution $\mathrm{x}($.$) of Eq. (8), provided$

$$
N=\int_{t_{0}}^{\infty}\left(l_{t}+\int_{t_{0}}^{t} k_{t, u} d \mu(u)\right) d t<\infty .
$$

Proof by Eq. (7) we have

$$
\begin{equation*}
x(t)=\Phi\left(t, t_{0}\right) x_{0}+\int_{\mathrm{t}_{0}}^{t} \Phi(t, \tau)\left(g \left(\tau, x(\tau)+\int_{\mathrm{t}_{0}}^{t} f(\tau, u, x(u) d \mu(u)) d \tau, \quad t \geq t_{0}\right.\right. \tag{10}
\end{equation*}
$$

By the assumptions, $\sup _{t \geq t_{0}}\left\|\Phi\left(t, t_{0}\right)\right\|=C_{0}<\infty$ and $f(t, s, x), g(t, x)$ are Lipschitz continuous in $x$ with the Lipschitz coefficients $l$. and $k_{\text {., }}$ respectively, we get

$$
\|x(t)\|=C_{0}\left\|x_{0}\right\|+C_{0} \int_{t_{0}}^{t}\left(\|x(\tau)\|+\int_{t_{0}}^{t} f(\tau, u, x(u) d \mu(u)) d \tau\right.
$$

By using Pachpatte inequality in Lemma 3.1 with $c_{1}=C_{0}\left\|x_{0}\right\|$ and $c_{2}=C_{0}$ we have

$$
\|x(t)\|=C_{0}\left\|x_{0}\right\| \exp \left\{C_{0} \int_{t_{0}}^{t}\left(l_{\tau}+\int_{t_{0}}^{t} k_{\tau, u}\|x(u)\| d \mu(u)\right) d \tau\right\}
$$

Thus, we get the estimate $x(t) \leq C_{0} e^{C_{0} N}\left\|x_{0}\right\|$, for all $t \geq t_{0}$. The proof is complete.
Example 3.3 Consider the equation

$$
\begin{equation*}
x^{\prime}(t)=-x(t)+\frac{1}{t^{2}} \int_{0}^{t} s x(s) d \mu(s), \quad t \geq 0 \tag{11}
\end{equation*}
$$

where $\mu()=.\sum_{n=1}^{\infty} \delta_{n}($.$) . Thus x_{0}>0$
i) When $0 \leq t \leq 1$, we have $x(t)=x_{0} e^{-t}$.
ii) When $1<t<2$, we have $x^{\prime}(t)=-x(t)+\frac{1}{t^{2}} x(1) \leq-x(t)+x(1)$, therefore $x(t) \leq x(1)=x(0) e^{-1}$.
iii) When $2 \leq t<2$, we have

$$
x^{\prime}(t)=-x(t)+\frac{1}{t^{2}}(2 x(2)+x(1)) \leq-x(s)+\frac{1}{2^{2}}(2 x(2)+x(1)) \leq-x(s)+x(1)
$$

which implies that $x(t) \leq x(1)=x(0) e^{-1}$.
iv) Continuing this way we have $x(t) \leq x(0) e^{-1}, \forall t \geq 0$. When $\mathrm{x}(0)<0$ we can prove by a similar way that $x(0) e^{-1} \leq x(t), \forall t \geq 0$. This means that the solution of (3.4) is bounded. Consider a perturbed equation

$$
x^{\prime}(t)=-x(t)+\frac{1}{t^{2}} \int_{0}^{t} s x(s) d \mu(s)+\int_{0}^{t} \frac{s}{1+t^{4}} \sin x(s) d \mu(s), \quad t \geq 0
$$

The function $f(t, s, x)=\frac{s \sin x(s)}{1+t^{4}}$ is Lipschitz continuous with the Lipschitz coefficient $k_{t, s}=\frac{s}{1+t^{4}}$. It is clear that

$$
\int_{0}^{t} k_{t, s} d \mu(s)=\sum_{n=1}^{[t]} \frac{n}{1+t^{4}} \leq \frac{t(t+1)}{2\left(1+t^{4}\right)} \leq \frac{2}{1+t^{4}}, \quad \text { and } \quad N=\int_{0}^{\infty} \int_{0}^{t} k_{t, s} d \mu(s) \leq \int_{0}^{t} \frac{2}{1+t^{2}} d t=\pi
$$

Thus, from theorem 3.2, it follows that the solution of Eq. (8) is bounded by $e^{\pi e^{-1}}$.
Next, we prove that the exponential stability implies $L_{p}$ stability under under small perturbations.
Definition 3.4 (See [2]) The trivial solution $x \equiv 0$ of Eq. (8) is said to be uniformly L_p-stable if there exist constants $M_{1}, M_{2}$ such that

$$
\begin{gather*}
\left\|x\left(t, t_{0}, x_{0}\right)\right\|_{\mathbb{R}^{n}} \leq M_{1}\left\|x_{0}\right\|_{\mathbb{R}^{n}, t \geq t_{0}}  \tag{12}\\
\left\|x\left(t, t_{0}, x_{0}\right)\right\|_{L_{p}\left(t_{0}, \infty\right)} \leq M_{2}\left\|x_{0}\right\|_{\mathbb{R}^{n}} \tag{13}
\end{gather*}
$$

Lemma 3.5 Let $1 \leq p, q<\infty, \frac{1}{p}+\frac{1}{q}=1$ and $\mathrm{U}(\mathrm{x}), \mathrm{V}(\mathrm{x})$ are positive functions. There is a finite C for which

$$
\begin{equation*}
\left[\int_{t_{0}}^{\infty}\left|U(x) \int_{t_{0}}^{x} f(t) \Delta t\right|^{p} \Delta x\right]^{\frac{1}{p}} \leq C\left[\int_{t_{0}}^{\infty}|V(x) f(x)|^{p} \Delta x\right]^{\frac{1}{p}}, \tag{14}
\end{equation*}
$$

is true for real f, where $B=\sup _{r>0}\left[\int_{r}^{\infty}|U(x)|^{p} \Delta x\right]^{\frac{1}{p}}\left[\int_{t_{0}}^{r}|V(x)|^{-q} \Delta x\right]^{\frac{1}{q}}$, (with the convention $0^{\infty}=\infty^{0}$ $=1$ ). Furthermore, if C is the least constant for which (14) holds, then $B \leq C \leq p^{\frac{1}{p}} q^{\frac{1}{q}} B$, for which $1<$ $p<\infty$ and $\mathrm{B}=\mathrm{C}$ if $p=1$ or $\infty$.

Remark 3.6 If we use $U(x)=V(x)=e^{\alpha x}$, then

$$
B=\sup _{r \in T_{t_{0}}}\left[\int_{r}^{\infty}\left(e^{\alpha s}\right)^{p} d s\right]^{\frac{1}{p}}\left[\int_{t_{0}}^{r}\left(e^{-\alpha s}\right)^{-q} d s\right]^{\frac{1}{q}} \leq \frac{1}{\alpha p^{\frac{1}{\bar{p}}} q^{\frac{1}{q}}} \text { and } \frac{1}{\alpha p^{\frac{1}{\bar{p}}} q^{\frac{1}{q}}} \leq C \leq \frac{1}{\alpha} .
$$

where $\eta_{\alpha}=\frac{\alpha_{1}}{1+\alpha_{2} \mu^{*}}$ and $\mu^{*}=\max \mu(t), \mathrm{t} \in \mathbf{T}$.

$$
\left[\int_{t_{0}}^{\infty}\left|e_{\theta \alpha}\left(t, t_{0}\right) \int_{t_{0}}^{t} f(s) \Delta s\right|^{p} \Delta t\right]^{\frac{1}{p}} \leq \frac{p^{\frac{1}{p}} q^{\frac{1}{q}}}{\eta_{\alpha}}\left[\int_{t_{0}}^{\infty}\left|e_{\theta \alpha}\left(t, t_{0}\right) f(t)\right|^{p} \Delta x\right]^{\frac{1}{p}}
$$

Theorem 3.7 Assume that Eq. (5) is exponentially stable and

$$
\operatorname{supl}_{t \geq t_{0}}+\sup _{t \geq t_{0}}\left(\int_{t}^{\infty} k_{t, u}^{p} d \tau\right)^{\frac{1}{p}}=m<\frac{1}{M C}
$$

with $\alpha$, M to be defined in Definition 2.3, and $C=C(\alpha)$ is defined in Remark 3.6 corresponding to the function $U(x)=V(x)=e^{\alpha x}$. Then, the solution $\theta$ of the perturbed equation

$$
\left\{\begin{array}{l}
x^{\prime}(t)=A(t) x(t)+\int_{t_{0}}^{t} H(t, s) x(s) d \mu(s)+\int_{t_{0}}^{t} f(t, s, x(s)) d s+g(t, x(t)), t \geq t_{0} \\
x\left(t_{0}\right)=x_{0} \in X
\end{array}\right.
$$

is uniformly $L_{p}$-stable.
Proof: By the variation of constants formula in Eq. (7), when $t \geq t_{0}$ one has

$$
\begin{gathered}
x(t)=\Phi\left(t, t_{0}\right) x_{0}+\int_{t_{0}}^{t} \Phi(t, \rho)\left(\int_{t_{0}}^{t} f(\rho, u, x(s) d s+g(\rho, x(\rho))) d \rho .\right. \\
\|x(t)\| \leq M e^{-\omega\left(t-t_{0}\right)}\left\|x_{0}\right\|+M \int_{t_{0}}^{t} e^{-\omega(t-\rho)}\left(\int_{t_{0}}^{t} k_{\rho, s}\|x(s)\| d s+l_{\rho}\|x(\rho)\| d \rho .\right.
\end{gathered}
$$

By using Hardy inequality first and then using Minkowski inequality we get

$$
\begin{aligned}
& \int_{t_{0}}^{T}\left(\int_{t_{0}}^{t} e^{-\omega(t-\rho)}\left(\int_{t_{0}}^{p} k_{\rho, s}\|x(s)\| d s\right) d \rho\right)^{\frac{1}{p}} \leq C \int_{t_{0}}^{T}\left(\left(\int_{t_{0}}^{\rho} k_{\rho, s}\|x(s)\| d s\right)^{p} d \rho\right)^{\frac{1}{p}} \\
& \quad \leq C\left(\int_{t_{0}}^{T}\|x(s)\|^{p} \int_{t_{0}}^{T}\left(k_{\rho, s}\right)^{p} d \rho d s\right)^{\frac{1}{p}} \leq C \sup _{t \geq t_{0}}\left(\int_{t}^{\infty}\left(k_{\tau, t}\right)^{p} d \tau\right)^{\frac{1}{p}}\left(\int_{t_{0}}^{T}\|x(s)\|^{p} d s\right)^{\frac{1}{p}} .
\end{aligned}
$$

Thus, from Eq. (7) we get

$$
\begin{aligned}
\|x(t)\|_{L_{p}\left[t_{0}, T\right]} \leq & \frac{M\left\|x_{0}\right\|}{(p \omega)^{1 / p}}+M\left[\int_{t_{0}}^{T}\left(\int_{t_{0}}^{t} e^{-\omega(t-\tau)}\left(\int_{t_{0}}^{\tau} k_{\tau, s}\|x(s)\| d s\right) d \tau\right)^{p} d t\right]^{\frac{1}{p}} \\
& +M\left[\int_{t_{0}}^{T}\left(\int_{t_{0}}^{t} e^{-\omega(t-\tau)} l_{\tau}\|x(\tau)\| d \tau\right)^{p} d t\right]^{\frac{1}{p}} \\
& \leq \frac{M\left\|x_{0}\right\|}{(p \omega)^{1 / p}}+M C \sup _{t \geq t_{0}}\left(\int_{t}^{\infty} k_{\tau, t} d \tau\right)^{\frac{1}{p}}\|x(.)\|_{L_{p}\left[t_{0}, T\right]}+\sup _{t \geq t_{0}} l_{t}\|x(.)\|_{L_{p}\left[t_{0}, T\right]} \\
& \leq \frac{M\left\|x_{0}\right\|}{(p \omega)^{1 / p}}+M C m\|x(.)\|_{L_{p}\left[t_{0}, T\right]}
\end{aligned}
$$

where $m=\sup l_{t}+\sup _{t \geq t_{0}}^{t \geq t_{0}}<\left(\int_{t}^{\infty} k_{\tau, t} d \tau\right)^{\frac{1}{p}}$. Hence,

$$
\|x(t)\|_{L_{p}\left[t_{0}, T\right]} \leq \frac{M\left\|x_{0}\right\|}{(1-M C m)(p \omega)^{1 / p}}
$$

Letting $T \rightarrow \infty$ obtains $\|x(t)\|_{L_{p}\left[t_{0}, \infty\right]} \leq \frac{M\left\|x_{0}\right\|}{(1-M C m)(p \omega)^{1 / p}}$. Thus we get (13).
We pass to prove (13). Using Holder inequality and Minkowski inequality we see that

$$
\begin{aligned}
\int_{t_{0}}^{t} e^{-\omega(t-\tau)}\left(\int_{t_{0}}^{\tau} k_{\tau, s}\|x(s)\| d s\right) d \tau & \leq e^{-\omega t}\left(\int_{t_{0}}^{t} e^{q \omega \tau} d \tau\right)^{\frac{1}{q}}\left(\int_{t_{0}}^{t}\left(\int_{t_{0}}^{\tau} k_{\tau, s}\|x(s)\| d s\right)^{p} d \tau\right)^{\frac{1}{p}} \\
& \leq \frac{1}{(q \omega)^{\frac{1}{q}}}\left(\int_{t_{0}}^{t}\|x(s)\|^{p}\left(\int_{s}^{t} k_{\tau, s} d \tau\right) d s\right)^{\frac{1}{p}} \\
& \leq \frac{1}{(q \omega)^{\frac{1}{q}}} \sup _{t \geq t_{0}}\left(\int_{t}^{\infty} k_{\tau, t} d \tau\right)^{\frac{1}{p}}\|x(.)\|_{L_{p}\left[t_{0}, t\right]} \\
& \leq \frac{M_{2}}{(q \omega)^{\frac{1}{q}} \sup _{t \geq t_{0}}\left(\int_{t}^{\infty} k_{\tau, t} d \tau\right)^{\frac{1}{p}}\left\|x\left(t_{0}\right)\right\|}
\end{aligned}
$$

Similarly,

Therefore,

$$
\begin{gathered}
\|x(t)\| \leq e^{-\omega\left(t-t_{0}\right)} M\left\|x\left(t_{0}\right)\right\|+M \int_{t_{0}}^{t} e^{-\omega(t-\tau)}\left(\int_{t_{0}}^{\tau} k_{\tau, s}\|x(s)\| d s+l_{\tau}\|x(\tau)\|\right) \mathrm{d} \tau \\
\leq M_{1}\left\|x\left(t_{0}\right)\right\|
\end{gathered}
$$

where $M_{1}=M+M M_{2}(q \omega)^{\frac{-1}{q}}\left(\sup _{t \geq t_{0}}\left(\int_{t}^{\infty} k_{\tau, t} d \tau\right)^{\frac{1}{p}}+\sup _{t \geq t_{0}} l_{t}\right)$. We have the proof.

## 4. Bohl-Perron Theorem

This section continues to study the Bohl-Perron Theorem by considering the exponent stability to Eq. (2) via properties of mapping between weighted spaces $L^{\gamma}\left(t_{0}\right)$ and $C^{\gamma}\left(t_{0}\right)$ defined below. We construct an operator N and show that the exponential stability of Eq. (5) is equivalent the fact that the operator N is surjective.

Let $\gamma \geq 0$. Define two families of Banach spaces $L^{\gamma}\left(t_{0}\right)$ and $C^{\gamma}\left(t_{0}\right)$ as

$$
\begin{aligned}
& L^{\gamma}\left(t_{0}\right)=\left\{f:\left[t_{0}, \infty\right) \rightarrow X, f \text { is measurable and } \int_{t_{0}}^{\infty} e^{\gamma t}\|f(t)\| d t<\infty\right\}, \\
& C^{\gamma}\left(t_{0}\right)=\left\{x:\left[t_{0}, \infty\right) \rightarrow X, x \text { is continous } x\left(t_{0}\right)=0 \text { and } \sup _{t \geq t_{0}}^{\gamma t}\|x(t)\|<\infty\right\},
\end{aligned}
$$

with the norms defined as follows

$$
\|f\|_{L^{\gamma}\left(t_{0}\right)}=\int_{t_{0}}^{\infty} e^{\gamma t}\|f(t)\| d t \quad \text { and } \quad\|x\|_{C^{\gamma}\left(t_{0}\right)}=\sup _{t \geq t_{0}}^{\gamma t}\|x(t)\| .
$$

When $\gamma=0$, the space $L^{0}\left(t_{0}\right)$ is $L_{1}\left(\left[t_{0}, \infty\right), X\right)$ consisting all integrable functions and $C^{0}\left(t_{0}\right)=$ $C_{b}\left(\left[t_{0}, \infty\right), X\right)$ is the set of all bounded continuous.

To simplify notations, we write $L^{\gamma}\left(t_{0}\right), C^{\gamma}\left(t_{0}\right)$ by $L^{\gamma}$ and $C^{\gamma}$ if there is no confusion. For any $f \in$ $L^{\gamma}$ we consider equation

$$
\begin{equation*}
x^{\prime}(t)=A(t) x(t)+\int_{t_{0}}^{t} H(t, s) x(s) d \mu(s)+f(t), \quad t \geq t_{0} \tag{15}
\end{equation*}
$$

with initial condition $x\left(t_{0}\right)=0$. As is mentioned in the function $x(t), t \geq t_{0}$ is a solution of (15) if and only if

$$
\begin{equation*}
x(t)=\int_{t_{0}}^{t}\left(A(\tau) x(\tau)+\int_{t_{0}}^{\tau} H(\tau, s) x(s) d \mu(s)+f(\tau)\right) d \tau, \quad t \geq t_{0} . \tag{16}
\end{equation*}
$$

By using the constant variation formula (7), the solution $\mathrm{x}(\mathrm{t})$ of (15) is expressed as

$$
\begin{equation*}
x(t)=\int_{t_{0}}^{t} \Phi(t, s) f(s) d s, t \geq t_{0} . \tag{17}
\end{equation*}
$$

Define $N_{s} f(t)=\int_{t_{0}}^{t} \Phi(t, s) f(s) d s, t \geq t_{0}, f \in L^{\gamma}(s)$. We write simply $N$ for $N_{t_{0}}$.
Theorem 4.1 For any $\gamma \geq 0$, if $N$ maps $L^{\gamma}$ to $C^{\gamma}$, then there exists a positive constant K such that for all $s \geq t_{0}$,

$$
\left\|N_{s}\right\| \leq K .
$$

Proof. Consider the case $s=t_{0}$. For every $t>t_{0}$, we define an operator $F_{t}: L^{\gamma} \rightarrow X$ by

$$
F_{t}(f(.))=e^{\gamma t} \int_{t_{0}}^{t} \Phi(t, s) f(s) d s=e^{\gamma t} N f(t) .
$$

By the assumption of Theorem, the operator $N$ maps $L^{\gamma}$ to $C^{\gamma}$. Therefore,

$$
\sup _{t \geq s}\left\|F_{t}(f)\right\|=\sup _{t \geq s} e^{\gamma t}\|L f(t)\|<\infty, \quad f \in L^{\gamma} .
$$

By using the Uniform Boundedness principle, we have $\sup _{t \geq t_{0}}\left\|F_{t}\right\|=K<\infty$. It is known that,

$$
\|N\|=\sup _{f \in L^{r}} \frac{\|N f\|_{C^{r}}}{\|f\|}=\sup _{f \in L^{r}} \frac{\sup _{t \geq 0}\left\|F_{t} f\right\|}{\|f\|}=\sup _{t \geq t_{0}}\left\|F_{t}\right\|=K .
$$

This means that we have the proof with $s=t_{0}$.

We pass to the case with arbitrary $s>t_{0}$. Let $\mathrm{f}(\mathrm{t})$ be a function in $L^{\gamma}(s)$. We extend the function f to a function $\bar{f}$ defined on $\left[t_{0}, \infty\right)$ as follows:

$$
\bar{f}= \begin{cases}0, & t_{0} \leq t \leq s \\ f(t), & t>s .\end{cases}
$$

It is seen that

$$
N \bar{f}(t)=\int_{0}^{t} \Phi(t, \tau) \bar{f}(\tau) d \tau=N_{s} f(t)
$$

Therefore, from (4.6) we get

$$
\left\|N_{s} f\right\|_{C^{\gamma}}=\sup _{t \geq s} e^{\gamma t}\left\|N_{s} f(t)\right\|=\sup _{t \geq t_{0}} e^{\gamma t}\|L \bar{f}(t)\|=\|L \bar{f}(t)\|_{C^{r}} \leq K\|\bar{f}\|_{L^{\gamma}}=K\|f\|_{L^{\gamma}(s)}
$$

The proof is complete.
Theorem 4.2 Let $\gamma>0$ be a positive number. The operator $N$ maps $L^{\gamma}$ to $C^{\gamma}$ if and only if Eq. (5) is $\gamma$-exponentially stable.

Proof. First, we prove the necessary condition. Suppose that $N$ maps $L^{\gamma}$ to $C^{\gamma}$. We show that then (5) is $\gamma$-exponentially stable.

From Theorem 4.1, we see that $N$ is a bounded operator from $L^{\gamma}$ to $C^{\gamma}$ with $\|N\|=K$. This means that if $f \in L^{\gamma}(s)$ and $0 \leq s \leq t$, then

$$
\begin{equation*}
e^{\gamma t}\left\|\int_{s}^{t} \Phi(t, u) f(u) d u\right\|=\|N f\|_{C^{\gamma}(s)} \leq K\|f\|_{L^{\gamma}(s)} \tag{18}
\end{equation*}
$$

Let $\gamma>0$ and $x \in X$, define the function

$$
f_{\sigma}(u)=\left\{\begin{array}{l}
\frac{1}{\rho} e^{-\frac{u-s}{\sigma}-\gamma u} v, u \geq s, \\
f(t), t_{0} \leq t \leq s .
\end{array}\right.
$$

By a simple calculation we have

$$
\int_{t_{0}}^{\infty} e^{\gamma u}\left\|f_{\sigma}(u)\right\| d u=\frac{1}{\sigma} \int_{t_{0}}^{\infty} e^{-\frac{u-s}{\sigma}}\|v\| d u=\|v\| .
$$

i.e., $f_{\sigma} \in L^{\gamma}$ and $\left\|f_{\sigma}\right\|_{L^{\gamma}}=\|v\|$. Moreover,

$$
\begin{aligned}
\lim _{\sigma \rightarrow 0} \int_{s}^{t} \Phi(t, u) f_{\sigma}(u) d u & =\lim _{\sigma \rightarrow 0} \int_{s}^{t} \Phi(t, u) \frac{1}{\sigma} e^{-\frac{u-s}{\sigma}-\gamma u} v d u \\
& =\lim _{\sigma \rightarrow 0} \int_{0}^{\frac{t-s}{\sigma}} \Phi(t, s+\sigma \square) e^{-\square-\gamma(s+\sigma \square)} v d \square=e^{-\gamma s} \Phi(t, s) v .
\end{aligned}
$$

Hence,

$$
e^{\gamma(t-s)}\|\Phi(t, s) v\|=e^{\gamma(t-s)} \lim _{\sigma \rightarrow 0}\left\|\int_{S}^{t} \Phi(t, u) f_{\sigma}(u) d u\right\| \leq K e^{-\gamma s}\left\|f_{\sigma}\right\|_{L^{\gamma}(s)}=e^{-\gamma s} K \leq K .
$$

Thus,

$$
\|\Phi(t, s)\| \leq K e^{-\gamma(t-s)}, \quad t \geq s \geq t_{0} .
$$

This means that Eq. (5) is uniformly asymptotically stable. We will prove the inverse relation. For any $f \in L^{\gamma}$, by (18) it yields

$$
e^{\gamma t}\|N f(t)\| \leq e^{\gamma t} \int_{t_{0}}^{t}\|\Phi(t, u)\|\|f(u)\| d u \leq M e^{\gamma t} \int_{t_{0}}^{t} e^{-\gamma(t-u)}\|f(u)\| d u
$$

$$
\leq M \int_{t_{0}}^{t} e^{\gamma u}\|f(u)\| d u \leq M\|f\|_{L^{\gamma}}<\infty
$$

Thus, $L f \in C^{\gamma}$ The proof is complete.
Remark 4.3 The argument dealt with in the proof of theorem 4.2 is still valid for $\gamma=0$. Thus, if L maps $L_{1}$ to $C_{b}$ then the solution of (5) with the initial condition $x(0)=0$ is bounded.

Corollary 4.4 The equation (5) is $\gamma$-exponentially stable if and only if the solution of

$$
\begin{equation*}
y^{\prime}(t)=A(t) y(t)+\gamma y(t)+\int_{t_{0}}^{t} H(t, \tau) e^{\gamma(t-\tau)} y(\tau) d \mu(\tau)+f(t), \quad t \geq t_{0} \tag{19}
\end{equation*}
$$

is bounded for all $f \in L^{\gamma}$.
Proof. Denote by $\Psi(t, s)$ the Cauchy operator of the homogeneous equation corresponding to (19), i.e., $\Psi(s, s)=I$ and

$$
\Psi^{\prime}(t, s)=A(t) \Psi(t, s)+\gamma \Psi(t, s)+\int_{t_{0}}^{t} H(t, \tau) e^{\gamma(t-\tau)} \Psi(\tau, s) d \mu(\tau)
$$

From (6) we get

$$
\frac{d}{d t}\left(e^{\gamma t} \Psi(t, s)\right)=A(t) e^{\gamma t} \Psi(t, s)+\gamma e^{\gamma t} \Psi(t, s)+\int_{t_{0}}^{t} H(t, \tau) e^{\gamma(t-\tau)} e^{\gamma \tau} \Psi(\tau, s) d \mu(\tau)
$$

The uniqueness of solutions says that $\Psi(t, s)=e^{\gamma t} \Phi(t, s)$.
Hence, the $\gamma$-exponential stability of (5) implies that the solution of (19) is bounded. Let $y(t)$ be the solution of (19) with the initial condition $y(0)=0$. By (18), this solution can be expressed as

$$
y(t)=\int_{0}^{t} \Psi(t, \tau) f(\tau) d \tau=e^{\gamma t} \int_{0}^{t} \Psi(t, \tau) f(\tau) d \tau=e^{\gamma t} N f(t)
$$

The boundedness of $y(t)$ says that $N$ maps $L^{\gamma}$ to $C^{\gamma}$. Therefore, by theorem 4.2, Eq. (5) is exponentially stable. The proof is complete.

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[^0]:    * Corresponding author.

    E-mail address: thuha@epu.edu.vn
    https//doi.org/10.25073/2588-1124/vnumap. 4820

